8.5. Wednesday for MAT4002

Reviewing. We can construct a continuous injection from |K| to |K'|, where $K = (V, \Sigma)$ is a simplicial complex, and $K' = (V', \Sigma')$ is its subcomplex:

Let $D_{\Sigma} := \coprod_{\sigma \in \Sigma} \sigma$ and $D_{\Sigma'} := \coprod_{\sigma' \in \Sigma'} \sigma'$, then $|K'| = D_{\Sigma'}/\sim_{\Sigma'}$ and $|K| = D_{\Sigma}/\sim_{\Sigma}$, which follows that

 $f: D_{\Sigma'} \to D_{\Sigma} \xrightarrow{P} D_{\Sigma} / \sim_{\Sigma}, P$ denotes the canonical projection mapping

The whole mapping f descends to a continuous mapping

$$\tilde{f}: D_{\Sigma'}/\sim_{\Sigma'} \to D_{\Sigma}/\sim_{\Sigma}$$

The \tilde{f} is injective since

$$x \sim_{\Sigma'} y \Longleftrightarrow i(x) \sim_{\Sigma} i(y), \qquad \forall x, y \in D_{\Sigma},$$
(8.6)

where *i* denotes the inclusion mapping.

Another way is to consider the inclusion $i : |K'| \to |K|$, which is continuous and injective as well. Note that i(|K'|) is closed in |K|.

Proposition 8.6 For each $K = (V, \Sigma)$, and finite *V*, there is a continuous injection $g : |K| \hookrightarrow \mathbb{R}^n$ for some *n*.

Proof. Consider $K^p := (V, \Sigma^p)$, where Σ^p is the power set of V. Therefore, $|K^p| = \Delta^{|V|-1} \subseteq \mathbb{R}^{|V|}$, and K is a simplicial subcomplex of K^p , which follows that

$$l: |K'| \xrightarrow{i} |K^p| \xrightarrow{i} \mathbb{R}^{|V|}$$

The whole mapping *l* is an inclusion mapping from |K'| to $\mathbb{R}^{|V|}$, which is continuous and injective. The proof is complete.

Proposition 8.7 — Hausdorff. If $K = (V, \Sigma)$ with finite *V*, then |K| is Hausdorff.

Proof. Let $g: |K| \xrightarrow{l} \mathbb{R}^n$. Consider the bijective $g: |K| \to g(|K|)$, which is continuous.

Sicne |K| is compact, and $g(|K|) \subseteq \mathbb{R}^n$ is Hausdorff, we imply that |K| and g(|K|) are homeomorphic, i.e., |K| is Hausdorff.

Definition 8.13 [Edge Path] An edge path of $K = (V, \Sigma)$ is a sequence of vertices $(v_1, \ldots, v_n), v_i \in V$ such that $\{v_i, v_{i+1}\} \in \Sigma, \forall i$.

Proposition 8.8 — Connectedness. Let $K = (V, \Sigma)$ be a simplicial complex. TFAE:

- 1. |K| is connected
- 2. |K| is path-connected
- 3. Any 2 vertices in (V, Σ) can be joined by an edge path, i.e., for $\forall u, v \in V$, there exists $v_1, \ldots, v_k \in V$ such that (u, v_1, \ldots, v_k, v) is an edge path.

Sketch of Proof (to be revised). 1. (3) implies (2): For every $x, y \in |K|$,

 $\begin{cases} x \in \Delta_{\sigma_1} \text{ for some } \sigma_1 \in \Sigma. \\ y \in \Delta_{\sigma_2} \text{ for some } \sigma_2 \in \Sigma. \end{cases}$

Take a path joining *x* to a vertex $v_1 \in \sigma_1$ and a path joining *y* to a vertex $v_2 \in \sigma_2$. By (3), we have a path joining v_1 and v_2 .

2. (1) implies (3): Suppose on the contrary that there is a vertex *v* not satisfying (3). Take *V*' as the set of vertexs that can be joined with *v*; and *V*'' as the set of vertexs that cannot be joinied with *v*.

Then $V', V'' \neq \emptyset$. Consider K', K'' be simplicial subcomplexes of K, spanned by V' and V''. Then |K'|, |K''| are disjoint, closed in |K|.

 $|K| = |K'| \cup |K''|$. If there exists $x \in |K| \setminus (|K'| \cup |K''|)$, then for any $\sigma \in \Sigma$ such that $x \in \Delta_{\sigma}$, we imply $\Delta_{\sigma} \not\subseteq |K'|$ or |K''|.

Therefore, σ consists of vertices in both V' and V''. Then there is $v', v'' \in \sigma$ joining V' and V''.

Therefore, there is no such *x* and hence $|K| = |K'| \cup |K''|$ is a disjoint union of two closed sets, i.e., not connected.

8.5.1. Homotopy

Yoneda's "philosophy". To understand an object *X* (in our focus, *X* denotes topological space), we should understand functions

$$f: A \to X$$
, or $g: X \to B$

One special example is to let $B = \mathbb{R}$.

There are many type of continuous mappings from *X* to *Y*. We will group all these mappings into equivalence classes.

Definition 8.14 [Homotopy] A **Homotopy** between two continuous maps $f, g: X \to Y$ is a continuous map

$$H: X \times [0,1] \rightarrow Y$$

such that

$$H(x,0) = f(x), \quad H(x,1) = g(x)$$

If such H exists, we say f and g are **homotopic**, denoted as $f \simeq g$.

• Example 8.7 Let $Y \subseteq \mathbb{R}^2$ be a convex subset. Consider two continuous maps $f: X \to Y$ and $g: X \to Y$. They are always homotopic since we can define the homotopy

$$H(x,t) = tg(x) + (1-t)f(x)$$

Proposition 8.9 Homotopy is an equivalent relation.

- *Proof.* 1. Let $f : X \to Y$ be any continuous map. Then $f \simeq f$: we can define a homotopy $H(x,t) = f(x), \forall 0 \le t \le 1$.
 - 2. Suppose $f \simeq g$, i.e., *H* is a homotopy between *f* and *g*, then $g \simeq f$: Define the mapping H'(x,t) = H(x,1-t), then

$$H'(x,0) = g(x), \quad H'(x,1) = f(x)$$

3. Let *f*, *g*, *h* : *X* → *Y* be three continuous maps. If *f* and *g* are homotopic and *g* and *h* are homotopic, then *f* and *h* are homotopic:
Let *H* : *X* × [0,1] → *Y* be a continuous map such that

$$H(x,0) = f(x), H(x,1) = g(x);$$

 $K: X \times [0,1] \rightarrow Y$ be a continuous map such that

$$K(x,0) = g(x), K(x,1) = h(x).$$

Define a function $J : X \times [0,1] \rightarrow Y$ by

$$J(x,t) = \begin{cases} H(x,2t), & 0 \le t \le 1/2\\ K(x,2t-1), & 1/2 \le t \le 1 \end{cases}$$

• *J* is continuous, since for all closed $V \subseteq Y$,

$$J^{-1}(V) = (J^{-1}(V) \cap (X \times [0, 1/2])) \cup (J^{-1}(V) \cap (X \times [1/2, 1])) = H^{-1}(V) \cup K^{-1}(V),$$

and the closedness of $H^{-1}(V)$ and $K^{-1}(V)$ implies the closedness of $J^{-1}(V)$

• Moreover, *J* has the property that J(x,0) = H(x,0) = f(x), while J(x,1) = K(x,1) = h(x).

R There are only one equivalence class in example (8.7). Actually, for given space *X* and *Y*, if any two continuous mapping are homotopic, then we imply there is only one equivalence class.