Chapter 9

Week9

9.1. Monday for MAT3040

Reviewing.

- $\mathcal{X}_T(x) = (x \lambda_1) \cdots (x \lambda_n)$ over \mathbb{F} if and only if *T* is triangularizable over \mathbb{F} .
- *m_T*(*x*) = (*x* − μ₁)···(*x* − μ_k), where μ_i's are distinct over 𝔽 if and only if *T* is diagonalizable over 𝔽.

The converse for this statement is the proposition (8.2). Let's focus on the proof for the forward direction.

9.1.1. Remarks on Primary Decomposition Theo-

rem

Theorem 9.1 — **Primary Decomposition Theorem.** Let $T: V \to V$ be a linear operator with dim $(V) < \infty$, and

$$m_T(x) = [p_1(x)]^{e_1} \cdots [p_k(x)]^{e_k}$$

where p_i 's are distinct, monic, irreducible polynomials. Let $V_i = \text{ker}(p_i(T)^{e_i})$, then

- 1. each V_i is *T*-invariant (*i.e.*, $T(V_i) \le V_i$)
- 2. $V = V_1 \oplus \cdots \oplus V_k$
- 3. $T \mid_{V_i}$ has the minimal polynomial $p_i(x)^{e_i}$.

Proof. 1. (1) follows from part (2) for example (??).

2. Let
$$q_i(x) = [p_1(x)]^{e_1} \cdots [\widehat{p_i(x)}]^{e_i} \cdots [p_k(x)]^{e_k} := m_T(x) / [p_i(x)]^{e_i}$$
, then it is clear that

- (a) $gcd(q_1,...,q_k) = 1$
- (b) $gcd(q_i, p_i^{e_i}) = 1$
- (c) $q_i \cdot p_i^{e_i} = m_T$
- (d) If $i \neq j$, then $m_T(x) \mid q_i(x)q_j(x)$
 - By (a) and Rezout's Theorem (**??**), there exists polynomials *a*₁,...,*a*_k such that

$$a_1(x)q_1(x) + \dots + a_k(x)q_k(x) = 1,$$

which implies

$$\underbrace{a_1(T)q_1(T)\boldsymbol{v}}_{\boldsymbol{v}_1} + \dots + \underbrace{a_k(T)q_k(T)\boldsymbol{v}}_{\boldsymbol{v}_k} = \boldsymbol{v}$$

Therefore, $\boldsymbol{v} = \boldsymbol{v}_1 + \cdots + \boldsymbol{v}_k$ for our constructed $\boldsymbol{v}_1, \dots, \boldsymbol{v}_k$.

• Note that

$$p_i(T)^{e_i} \boldsymbol{v}_i = p_i(T)^{e_i} a_i(T) q_i(T) \boldsymbol{v} = a_i(T) [q_i(T) p_i(T)^{e_i}] \boldsymbol{v} = a_i(T) m_T(T) \boldsymbol{v} = \boldsymbol{0},$$

which implies $\boldsymbol{v}_i \in \ker([p_i(T)]^{e_i}) := V_i$, and therefore

$$V = V_1 + \dots + V_k \tag{9.1}$$

• To show that the summation in (9.1) is essentially the direct sum, consider

$$\mathbf{0} = \mathbf{v}_1' + \dots + \mathbf{v}_{k'} \quad \forall \mathbf{v}_i' \in V_i. \tag{9.2}$$

By (a) and Rezout's Theorem (??), there exists $b_i(x), c_i(x)$ such that

$$b_i(x)q_i(x) + c_i(x)p_i(x)^{e_i} = 1 \implies b_i(T)q_i(T) + c_i(T)p_i(T)^{e_i} = I_i$$

i.e.,

$$b_i(T)q_i(T)\boldsymbol{v}'_i+c_i(T)p_i(T)^{e_i}\boldsymbol{v}'_i=b_i(T)q_i(T)\boldsymbol{v}'_i=\boldsymbol{v}'_i.$$

Appying the mapping $b_i(T)q_i(T)$ into equality (9.2) both sides, i = 1, ..., k, we obtain

$$\mathbf{0} = b_i(T)q_i(T)\mathbf{0} = b_i(T)q_i(T)\mathbf{v}'_1 + \dots + b_i(T)q_i(T)\mathbf{v}'_k$$

Note that all terms on RHS vanish except for $b_i(T)q_i(T)\boldsymbol{v}'_i = \boldsymbol{v}'_i$, since $q_i(x) = [p_1(x)]^{e_1} \cdots [\widehat{p_i(x)}]^{e_i} \cdots [p_k(x)]^{e_k}$ and $\boldsymbol{v}'_j \in \ker([p_j(x)]^{e_j})$. Therefore, $\boldsymbol{v}'_i = 0$ for i = 1, ..., k, i.e., $V = V_1 \oplus \cdots \oplus V_k$.

3. For any $\boldsymbol{v}_i \in V_i$, we have $p_i(T)^{e_i} \boldsymbol{v}_i = \boldsymbol{0}$, which implies $m_{T|V_i}(x) \mid p_i(x)^{e_i}$. Together with Corollary (8.1), $m_{T|v_i}(x) = p_i(x)^{f_i}$ for some $1 \le f_i \le e_i$.

Suppose on the contrary that there exists $f_i < e_i$ for some *i*, consider any $\boldsymbol{v} := \boldsymbol{v}_1 + \cdots + \boldsymbol{v}_k \in V$, and

$$p_1(T)^{f_1}\cdots p_k(T)^{f_k}\boldsymbol{v} = p_1(T)^{f_1}\cdots p_k(T)^{f_k}(\boldsymbol{v}_1+\cdots+\boldsymbol{v}_k)$$

The term on the RHS vanishes since $p_i(T)^{f_j} \boldsymbol{v}_j = \boldsymbol{0}$, which implies

$$m_T \mid p_1^{f_1} \cdots p_k^{f_k},$$

but there exists *i* such that $e_i > f_i$, which is a contradiction.

Corollary 9.1 If $m_i(x) = (x - \mu_1) \cdots (x - \mu_k)$ over \mathbb{F} , where μ_i 's are distinct, then T is diagonalizable over \mathbb{F} . (the converse actually also holds, see proposition (8.2))

Proof. By primary decomposition theorem,

$$V = \underbrace{\ker(T - \mu_1 I)}_{V_1} \oplus \cdots \underbrace{\oplus \ker(T - \mu_k I)}_{V_k}$$

Take B_i as a basis of V_i , an μ_i -eigenspace of T. Then $B := \bigcup_{i=1}^k B_i$ is a basis consisting of eigenvectors of T.

It's clear that $(T |_{V_i})_{\mathcal{B},\mathcal{B}} = \text{diag}(\mu_i, \dots, \mu_i)$, and *T* is diagonalizable with

$$(T)_{\mathcal{B},\mathcal{B}} = \operatorname{diag}((T \mid_{V_1})_{\mathcal{B},\mathcal{B}}, \cdots, (T \mid_{V_k})_{\mathcal{B},\mathcal{B}}).$$

Corollary 9.2 [Spectral Decomposition] Suppose $T: V \to V$ is diagonalizable, then there exists a linear operator $p_i: V \to V$ for $1 \le i \le k$ such that

• $p_i^2 = p_i$ (idempotent)

•
$$p_i p_j = 0, \forall i \neq j$$

•
$$\sum_{i=1}^{k} p_i = I$$

•
$$p_i T = T p_i, \forall i$$

and scalars μ_1, \ldots, μ_k such that

$$T = \mu_1 p_1 + \dots + \mu_k p_k$$

Proof. Diagonlization of *T* is equivalent to say that $m_T(x) = (x - \mu_1) \cdots (x - \mu_k)$, where μ_i 's are distinct. Construct

- $V_i := \ker(T \mu_i I)$
- *p_i*: *V* → *V* given by *p_i* = *a_i*(*T*)*q_i*(*T*) as in the proof of primary decomposition theorem

Then:

- $p_i T = T p_i$ is obvious
- $\sum_{i=1}^{k} p_i = \sum_{i=1}^{k} a_i(T)q_i(T) = I$
- $p_i p_j = a_i(T)a_j(T)q_i(T)q_j(T) := a_i(T)a_j(T)s(T)m_T(T) = \mathbf{0}$
- $p_i^2 = p_i(p_1 + \dots + p_k) = p_i \cdot I = p_i$

For the last part, note that

• $p_i V \leq V_i, \forall i$: for $\forall \boldsymbol{v} \in V$,

$$(T - \mu_i I)p_i \boldsymbol{v} = (T - \mu_i I)a_i(T)q_i(T)\boldsymbol{v} = a_i(T)m_T(x)\boldsymbol{v} = \boldsymbol{0}$$

Therefore, $p_i V \leq \ker(T - \mu_i I) = V_i$

• Now, for all $\boldsymbol{w} \in V$,

$$T\boldsymbol{w} = T(p_1 + \dots + p_k)\boldsymbol{w}$$
$$= Tp_1\boldsymbol{w} + \dots + Tp_k\boldsymbol{w}$$
$$= (\mu_1p_1)\boldsymbol{w} + \dots + (\mu_kp_k)\boldsymbol{w}$$

and therefore $T = \mu_1 p_1 + \cdots + \mu_k p_k$

Organization of future two weeks. We are interested in under which condition does the *T* is diagonalizable. One special case is T = A, where **A** is a symmetric matrix. We will study normal operators, which includes the case for symmetric matrices.

Question: what happens if $m_T(x)$ contains repeated linear factors? We will spend the next whole class to show the Jordan Normal Form:

Theorem 9.2 — **Jordan Normal Form.** Let \mathbb{F} be algebraically closed field such that every linear operator $T: V \to V$ has the form

$$m_T(x) = \prod_{i=1}^k (x - \lambda_i)^{e_i}$$

where λ_i 's are distinct.

Then there exists basis \mathcal{A} of V such that

$$(T)_{\mathcal{A},\mathcal{A}} = \operatorname{diag}(\boldsymbol{J}_1,\ldots,\boldsymbol{J}_k)$$

where	$\boldsymbol{J}_{i} = \begin{pmatrix} \mu & 1 & 0 & 0 \\ 0 & \mu & 1 & 0 \\ 0 & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \mu \end{pmatrix}$	
for some $\mu \in \{\lambda_1, \dots, \lambda_k\}$		