4.2. Monday for MAT3006

Our first quiz will be held on next Wednesday.

Reviewing.

• Picard Lindelof Theorem on ODEs. e.g., consider

$$\begin{cases} \frac{dy}{dx} = \frac{x}{1-y}, \ (x,y) \in G := (-\infty,\infty) \times (-\infty,1) \\ y(0) = 2 \end{cases}$$

Since $f \in C^1(G)$ satisfies the Lipschitz condition on some closed ball of the point (x_0, y_0) , the setting for Picard Lindelof Theorem is satisfied, and the solution is uniquely given by:

$$y = 1 + \sqrt{1 - x^2}, -1 < x < 1.$$

Therefore, the maximal interval of existence is given by (-1,1). In order to restrict *G* to be open to construct a closed ball of (x_0, y_0) , we need the initial condition $y(0) \neq 1$.

4.2.1. Generalization into System of ODEs

Formal Setting of System of ODEs. Consider the system of ODEs

$$\begin{cases} y_1'(x) = f_1(x, y_1(x), \dots, y_n(x)) \\ \vdots \\ y_n'(x) = f_n(x, y_1(x), \dots, y_n(x)) \end{cases} \begin{cases} y_1(\alpha) = \beta_1 \\ \vdots \\ y_n(x) = \beta_n \end{cases}$$

It's convenient to denote

$$\boldsymbol{y}(x) = \begin{pmatrix} y_1(x) \\ \vdots \\ y_n(x) \end{pmatrix} \in \mathcal{C}(\mathbb{R}, \mathbb{R}^n), \quad \boldsymbol{f}(x, \boldsymbol{y}) = \begin{pmatrix} f_1(x, \boldsymbol{y}) \\ \vdots \\ f_n(x, \boldsymbol{y}) \end{pmatrix}, \quad \boldsymbol{\beta} := \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_n \end{pmatrix}$$

Here the notation C(X,Y) denotes the set of bounded continuous mapping from X to Y. Therefore we can express the system of ODE as a compact form:

$$\begin{cases} \mathbf{y}' = \mathbf{f}(x, \mathbf{y}) \\ \mathbf{y}(\alpha) = \mathbf{\beta} \end{cases}$$

Generalization of Picard Lindelof Theorem. Consider the rectangle

$$S = \{ (\boldsymbol{x}, \boldsymbol{y}) \in \mathbb{R} \times \mathbb{R}^n \mid \alpha - a \le x \le \alpha + a, \beta_i - b_i \le y_i \le \beta_i + b_i, i = 1, \dots, n \}$$

Suppose that

•
$$\|\boldsymbol{f}(x,\boldsymbol{y})\| \leq M, \forall (x,\boldsymbol{y}) \in S$$

•
$$\|\boldsymbol{f}(x,\boldsymbol{y}) - \boldsymbol{f}(x,\boldsymbol{y}')\| \le L \cdot \|\boldsymbol{y} - \boldsymbol{y}'\|$$
 for $\forall x \in [\alpha - a, \alpha + a]$

Then consider the complete metric space

$$X = \{ \boldsymbol{y} \in \mathcal{C}([\alpha - a, \alpha + a], \mathbb{R}^n) \mid \beta_i - b_i \leq y_i(x) \leq \beta_i + b_i \}$$

(Verification of completeness: if *Y* is complete, then C(X, Y) is complete.) Under this setting, the similar argument gives the Picard-Lindelof for system of ODEs.

Higher Order ODEs. Note that there is a standard way to transform the ODE with higher order derivatives into a system of first order ODEs. Suppose we want to solve the initival value problem

$$\begin{cases} y^{(m)} = f(x, y, y', \dots, y^{(m-1)}) \\ y(\alpha) = \beta_0, \ y'(\alpha) = \beta_1, \dots, y^{(m-1)}(\alpha) = \beta_{m-1} \end{cases}$$

We can define the variables

$$\begin{pmatrix} y_{m-1}(x) \\ \vdots \\ y_1(x) \\ y_0(x) \end{pmatrix} = \begin{pmatrix} y^{(m-1)}(x) \\ \vdots \\ y'(x) \\ y(x) \end{pmatrix}$$

which gives an equivalent system of ODE:

$$\begin{cases} y'_{m-1} = f(x, y_0, \dots, y_{m-1}) \\ y'_{m-2} = y_{m-1} \\ \vdots \\ y'_0 = y_1 \end{cases}, \text{ with } \begin{cases} y_{m-1}(\alpha) = \beta_{m-1} \\ y_{m-2}(\alpha) = \beta_{m-2} \\ \vdots \\ y_0(\alpha) = \beta_0 \end{cases}$$

4.2.2. Stone-Weierstrass Theorem

Under the compact metric space *X*, the goal is to approximate **any** functions in C(X). For example, under X = [a, b], one can apply Taylor polynomials $p_n(x)$ to approximate differentiable functions:

$$||f(x) - p_n(x)||_{\infty} < \varepsilon$$
, for large *n*.

To formally describe the phenomenon for the approximation of **any** functions in C(X), we need to describe the set of approximate functions, which usually obtains a common property:

Definition 4.3 [Algebra] A subset $\mathcal{A} \subseteq \mathcal{C}(X)$ (where X is a general space) is an **algebra** if the following holds: • If $f_1, f_2 \in A$, then $\alpha f_1 + \beta f_2 \in A$ • If $f_1, f_2 \in A$, then $f_1 \cdot f_2 \in A$

■ Example 4.1 1. A = C(X) is an algebra.
2. X = [a,b], then A = P[a,b] = {All polynomials p(x)} is an algebra.

The goal is to approximate any $f \in C(X)$ by $p \in A$, i.e., for $\forall f \in C(X)$, there exists $p \in \mathcal{A}$ such that

$$\|f-p\|_{\infty} < \varepsilon, \ \forall \varepsilon > 0.$$

In other words, we aim to find an algebra $\mathcal{A} \subseteq \mathcal{C}(X)$ such that $\overline{\mathcal{A}} = \mathcal{C}(X)$, i.e., \mathcal{A} is dense in $\mathcal{C}(X)$.

Theorem 4.2 — Weierstrass Approximation. $\mathcal{P}[a,b]$ is dense in $\mathcal{C}[a,b]$.

Proof. Consider any function $f \in C[0,1]$. By rescaling, assume that $f \in C[0,1]$. By subtracting a linear function $\ell(x)$, assume that f(0) = f(1) = 0. Then we extend f(x)into \mathbb{R} by setting $f(x) = 0, \forall x \notin [0, 1]$.

• Step 1: Construction of approximate function: Consider the Landaus kernel function 1

$$Q_n(x) = \begin{cases} c_n \cdot (1 - x^2)^n, & -1 \le x \le 1\\ 0, & |x| > 1 \end{cases}$$

where c_n is chosen such that $\int Q_n(x) dx = 1$. Then construct the approximation of *f* by defining

$$p_n(x) := Q_n * f = \int_{-1}^{1} f(x+t)Q_n(t) dt$$

The intuition behind this construction is that as $n \to \infty$, $Q_n(x) \to \delta(x)$, where

$$\delta(x) = \begin{cases} \infty, & x = 0 \\ 0, & x \neq 0 \end{cases} \implies \int_{-1}^{1} f(x+t)\delta(t) \, \mathrm{d}t = f(x). \end{cases}$$

Step 2: Argue that $p_n(x) \in \mathcal{P}[a,b]$ **:** Now it's clear that

$$p_n(x) = \int_{-1}^{1} f(x+t)Q_n(t) dt$$
(4.2a)

$$= \int_{-x}^{1-x} f(x+t)Q_n(t) dt$$
 (4.2b)

$$= \int_{-1}^{1} f(u) \cdot Q_n(u-x) \, \mathrm{d}u$$
 (4.2c)

$$= \int_{-1}^{1} f(u) \cdot (1 - (u - x)^2)^n \,\mathrm{d}u, \tag{4.2d}$$

where (4.2b) is because that f = 0, for $x \notin [0,1]$ and $Q_n = 0$ for |x| > 1; (4.2c) is by change of variables; and (4.2d) is by substitution of $Q_n(x)$. Therefore, p_n is still a polynomial of x.

• Step 3: Construct an upper bound on *c_n*: It's clear that

$$c_n^{-1} = \int_{-1}^1 (1 - x^2)^n dx$$

= $2 \int_0^1 (1 - x^2)^n dx$
 $\ge 2 \int_0^1 (1 - nx^2) dx$
 $\ge 2 \int_0^{1/\sqrt{n}} (1 - nx^2) dx$
= $2(\frac{1}{\sqrt{n}} - \frac{1}{3\sqrt{n}}) > \frac{1}{\sqrt{n}}$

and therefore $c_n < \sqrt{n}$. As a result, for any fixed $\delta \in (0,1)$, we imply

$$Q_n(x) \leq \sqrt{n}(1-\delta^2)^n, \quad \forall x \in [\delta,1],$$

which implies $Q_n(x) \to 0$ uniformly on $[\delta, 1]$.

Step 4: Show that ||*p_n* − *f*||_∞ → 0. Since *f* is continuous, for given ε > 0, there exists δ ∈ (0,1) such that

$$|f(x) - f(y)| < \varepsilon$$
, when $|x - y| < \delta, x, y \in [0, 1]$.

Therefore, for any $x \in [0,1]$, and for sufficiently large *n*,

$$|p_n(x) - f(x)| = \left| \int_{-1}^{1} f(x+t) Q_n(t) - \int_{-1}^{1} f(x) Q_n(t) dt \right|$$
(4.3a)

$$\leq \int_{-1}^{1} |f(x+t) - f(x)| Q_n(t) dt$$
(4.3b)

$$\leq 2M \int_{-1}^{-\delta} Q_n(t) \,\mathrm{d}t + \frac{\varepsilon}{2} \int_{-\delta}^{\delta} Q_n(t) \,\mathrm{d}t + 2M \int_{\delta}^{1} Q_n(t) \,\mathrm{d}t \qquad (4.3c)$$

$$\leq 4M\sqrt{n}(1-\delta^2)^n + \frac{\varepsilon}{2} \tag{4.3d}$$

$$\leq \varepsilon$$
 (4.3e)

where (4.3c) is by separating the integrand into three parts, and then upper bounding |f(x + t) - f(x)| by $2M := 2\sup_x |f(x)|$ for the integrand $t \in [-1, \delta) \cup$ $(\delta, 1]$, and upper bounding |f(x + t) - f(x)| by $\frac{\varepsilon}{2}$ due to the continuity of ffor the integrand $t \in [\delta, \delta]$; (4.3e) is by choosing n sufficiently enough to make $4M\sqrt{n}(1 - \delta^2)^n$ sufficiently small.

Therefore $||p_n - f||_{\infty} = \max_{x \in [0,1]} |p_n(x) - f(x)| < \varepsilon$ for large *n*. The proof is complete.