1.2. Monday for MAT3006

1.2.1. Overview on uniform convergence

Definition 1.3 [Convergence] Let $f_n(x)$ be a sequence of functions on an interval $I = [a,b]$. Then $f_n(x)$ converges **pointwise** to $f(x)$ (i.e., $f_n(x_0) \to f(x_0)$) for $\forall x_0 \in I$, if

$$\forall \varepsilon > 0, \exists N_{x_0,\varepsilon} \text{ such that } |f_n(x_0) - f(x_0)| < \varepsilon, \forall n \geq N_{x_0,\varepsilon}$$

We say $f_n(x)$ converges uniformly to $f(x)$, (i.e., $f_n(x) \rightrightarrows f(x)$) for $\forall x_0 \in I$, if

$$\forall \varepsilon > 0, \exists N_{\varepsilon} \text{ such that } |f_n(x_0) - f(x_0)| < \varepsilon, \forall n \geq N_{\varepsilon}$$

■

■ **Example 1.6** It is clear that the function $f_n(x) = \frac{n}{1+nx}$ converges pointwise into $f(x) = \frac{1}{x}$ on $[0,\infty)$, and it is uniformly convergent on $[1,\infty)$. ■

Proposition 1.2 If $\{f_n\}$ is a sequence of continuous functions on I, and $f_n(x) \rightrightarrows f(x)$, then the following results hold:

1. $f(x)$ is continuous on I.
2. f is (Riemann) integrable with $\int_a^b f_n(x)\,\mathrm{d}x \to \int_a^b f(x)\,\mathrm{d}x$.
3. Suppose furthermore that $f_n(x)$ is **continuously differentiable**, and $f_n'(x) \rightrightarrows g(x)$, then $f(x)$ is differentiable, with $f_n'(x) \to f'(x)$.

We can put the discussions above into the content of series, i.e., $f_n(x) = \sum_{k=1}^n S_k(x)$.

Proposition 1.3 If $S_k(x)$ is continuous for $\forall k$, and $\sum_{k=1}^n S_k \rightrightarrows \sum_{k=1}^\infty S_k$, then

1. $\sum_{k=1}^\infty S_k(x)$ is continuous,
2. The series $\sum_{k=1}^\infty S_k$ is (Riemann) integrable, with $\sum_{k=1}^\infty \int_a^b S_k(x)\,\mathrm{d}x = \int_a^b \sum_{k=1}^\infty S_k(x)\,\mathrm{d}x$
3. If $\sum_{k=1}^n S_k$ is continuously differentiable, and the derivative of which is uniform

convergent, then the series $\sum_{k=1}^{\infty} S_k$ is differentiable, with

$$\left(\sum_{k=1}^{\infty} S_k(x)\right)' = \sum_{k=1}^{\infty} S_k'(x)$$

Then we can discuss the properties for a special kind of series, say power series.

Proposition 1.4 Suppose the power series $f(x) = \sum_{k=1}^{\infty} a_k x^k$ has radius of convergence R, then

1. $\sum_{k=1}^{n} a_k x^k \rightrightarrows f(x)$ for any $[-L, L]$ with $L < R$.
2. The function $f(x)$ is continuous on $(-R, R)$, and moreover, is differentiable and (Riemann) integrable on $[-L, L]$ with $L < R$:

$$\int_0^x f(t)\,\mathrm{d}t = \sum_{k=1}^{\infty} \frac{a_k}{k+1} x^{k+1}$$
$$f'(x) = \sum_{k=1}^{\infty} k a_k x^{k-1}$$

1.2.2. Introduction to MAT3006

What are we going to do.

1. (a) Generalize our study of (sequence, series, functions) on $\mathbb{R}^n$ into a metric space.
   (b) We will study spaces outside $\mathbb{R}^n$.

   Remark:

   - For (a), different metric may yield different kind of convergence of sequences. For (b), one important example we will study is $X = \mathcal{C}[a,b]$ (all continuous functions defined on $[a,b]$.) We will generalize X into $\mathcal{C}_b(E)$, which means the set of bounded continuous functions defined on $E \subseteq \mathbb{R}^n$.
   - The insights of analysis is to find a **unified** theory to study sequences/series on a metric space X, e.g., $X = \mathbb{R}^n, \mathcal{C}[a,b]$. In particular, for $\mathcal{C}[a,b]$, we will see that
     - most functions in $\mathcal{C}[a,b]$ are nowhere differentiable. (repeat part of

content in MAT2006)

- We will prove the existence and uniqueness of ODEs.
- the set $\text{poly}[a,b]$ (the set of polynomials on $[a,b]$) is dense in $\mathcal{C}[a,b]$. (analogy: $\mathbb{Q} \subseteq \mathbb{R}$ is dense)

2. Introduction to the Lebesgue Integration.

   For convergence of integration $\int_a^b f_n(x)\,\mathrm{d}x \to \int_a^b f(x)$, we need the pre-conditions (a) $f_n(x)$ is continuous, and (b) $f_n(x) \rightrightarrows f(x)$. The natural question is that can we relax these conditions to

   (a) $f_n(x)$ is integrable?

   (b) $f_n(x) \to f(x)$ pointwisely?

   The answer is yes, by using the tool of Lebesgue integration. If $f_n(x) \to f(x)$ and $f_n(x)$ is Lebesgue integrable, then $\int_a^b f_n(x)\,\mathrm{d}x \to \int_a^b f(x)\,\mathrm{d}x$, which is so called the **dominated convergence**.

1.2.3. Metric Spaces

We will study the **length** of an element, or the **distance** between two elements in an arbitrary set X. First let's discuss the length defined on a well-structured set, say vector space.

Definition 1.4 [Normed Space] Let X be a vector space. A **norm** on X is a function $\|\cdot\| : X \to \mathbb{R}$ such that

1. $\|\boldsymbol{x}\| \geq 0$ for $\forall \boldsymbol{x} \in X$, with equality iff $\boldsymbol{x} = \mathbf{0}$
2. $\|\alpha \boldsymbol{x}\| = |\alpha| \|\boldsymbol{x}\|$, for $\forall \alpha \in \mathbb{R}$ and $\boldsymbol{x} \in X$.
3. $\|\boldsymbol{x} + \boldsymbol{y}\| \leq \|\boldsymbol{x}\| + \|\boldsymbol{y}\|$ (triangular inequality)

Any vector space equipped with $\|\cdot\|$ is called a **normed space**.

■ **Example 1.7** 1. For $X = \mathbb{R}^n$, define

$$\|\boldsymbol{x}\|_2 = \left(\sum_{i=1}^n x_i^2\right)^{1/2} \quad \text{(Euclidean Norm)}$$

$$\|\boldsymbol{x}\|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p} \quad (p\text{-norm})$$

2. For $X = \mathcal{C}[a,b]$, define

$$\|f\|_\infty = \max_{x\in[a,b]} |f(x)|$$

$$\|f\|_p = \left(\int_a^b |f(x)|^p \, \mathrm{d}x\right)^{1/p}$$

Exercise: check the norm defined above are well-defined. ■

Here we can define the distance in an arbitrary set:

Definition 1.5 A set X is a **metric space** with metric (X,d) if there exists a (distance) function $d : X \times X \to \mathbb{R}$ such that

1. $d(\boldsymbol{x},\boldsymbol{y}) \geq 0$ for $\forall \boldsymbol{x},\boldsymbol{y} \in X$, with equality iff $\boldsymbol{x} = \boldsymbol{y}$.
2. $d(\boldsymbol{x},\boldsymbol{y}) = d(\boldsymbol{y},\boldsymbol{x})$.
3. $d(\boldsymbol{x},\boldsymbol{z}) \leq d(\boldsymbol{x},\boldsymbol{y}) + d(\boldsymbol{y},\boldsymbol{z})$.

■

■ **Example 1.8** 1. If X is a normed space, then define $d(\boldsymbol{x},\boldsymbol{y}) = \|\boldsymbol{x}-\boldsymbol{y}\|$, which is so called the metric induced from the norm $\|\cdot\|$.

2. Let X be any (non-empty) set with $\boldsymbol{x},\boldsymbol{y} \in X$, the discrete metric is given by:

$$d(\boldsymbol{x},\boldsymbol{y}) = \begin{cases} 0, & \text{if } x = y \\ 1, & \text{if } x \neq y \end{cases}$$

Exercise: check the metric space defined above are well-defined. ■

R Adopting the infinite norm discussed in Example (1.7), we can define a metric on $\mathcal{C}[a,b]$ by

$$d_\infty(f,g) = \|f-g\|_\infty := \max_{x\in[a,b]} |f(x)-g(x)|$$

which is the correct metric to study the uniform convergence for $\{f_n\} \subseteq \mathcal{C}[a,b]$.

Definition 1.6 Let (X,d) be a metric space. An **open ball** centered at $\boldsymbol{x} \in X$ of radius r is the set

$$B_r(\boldsymbol{x}) = \{\boldsymbol{y} \in X \mid d(\boldsymbol{x},\boldsymbol{y}) < r\}.$$

■ **Example 1.9** 1. For $X = \mathbb{R}^2$, we can draw the $B_1(\mathbf{0})$ with respect to the metrics d_1, d_2:

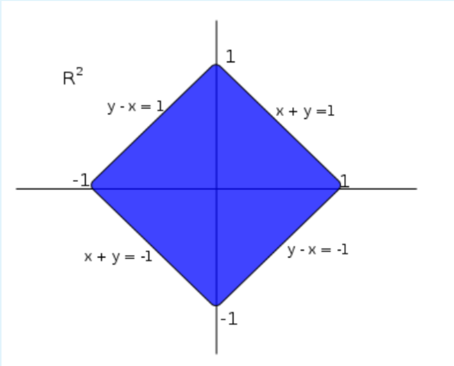

Figure 1.1: $B_1(\mathbf{0})$ w.r.t. the metric d_1

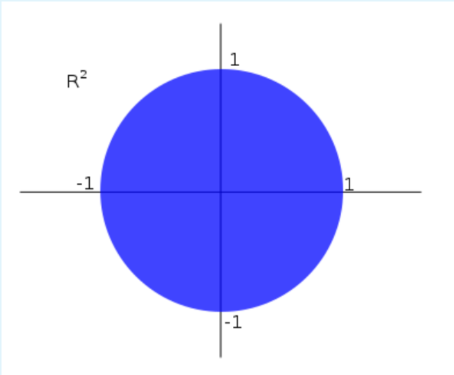

Figure 1.2: $B_1(\mathbf{0})$ w.r.t. the metric d_2