


Half-time review

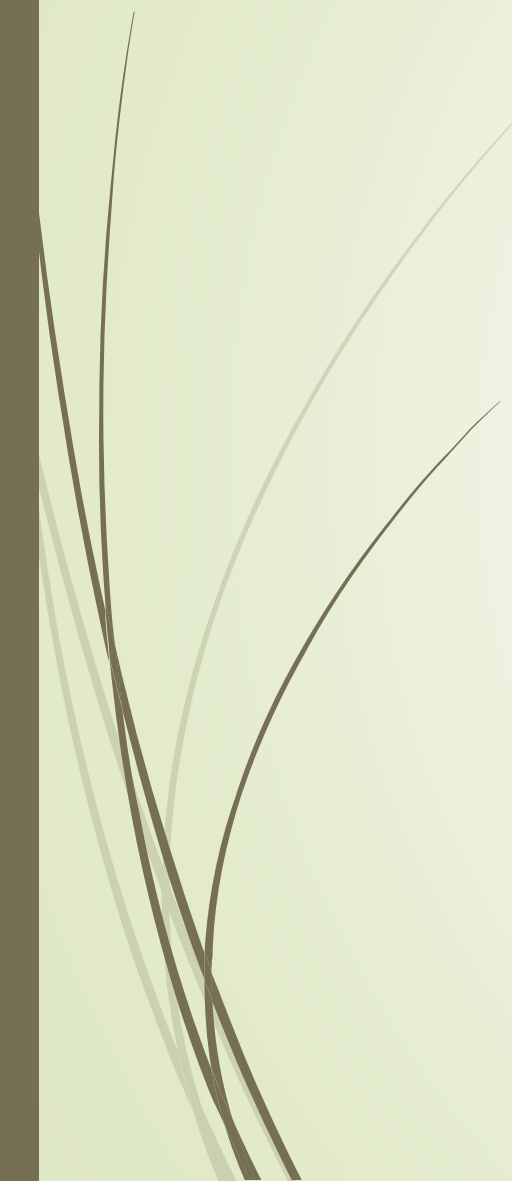
Instructor: Jie Wang

H. Milton Stewart School of
Industrial and Systems Engineering
Georgia Tech





Outline

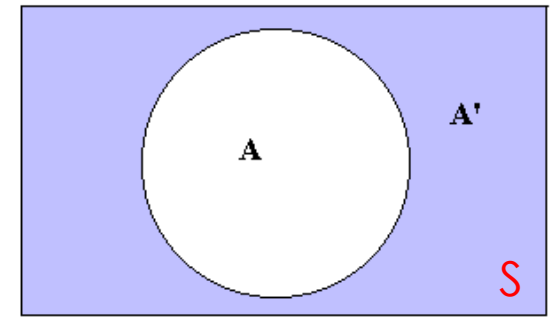
1. Probability Theory
 2. Univariate Random Variable
 3. Bivariate Random Variable
 4. Normal distribution
- 

What is probability theory?

Probability theory is the branch of mathematics concerned with probability, the analysis of **random phenomena** - wikipedia

1. Random experiment
2. Sample space
3. Event

} Set theory



➤ Random experiment

Any procedure that can be repeated infinitely and has **more than one** possible outcomes.

➤ Sample space

The collection of **all possible** outcomes and is denoted by **S** in this course.

➤ Event

The collection of **some possible** outcomes in **S** and is a subset of the sample space **S**.

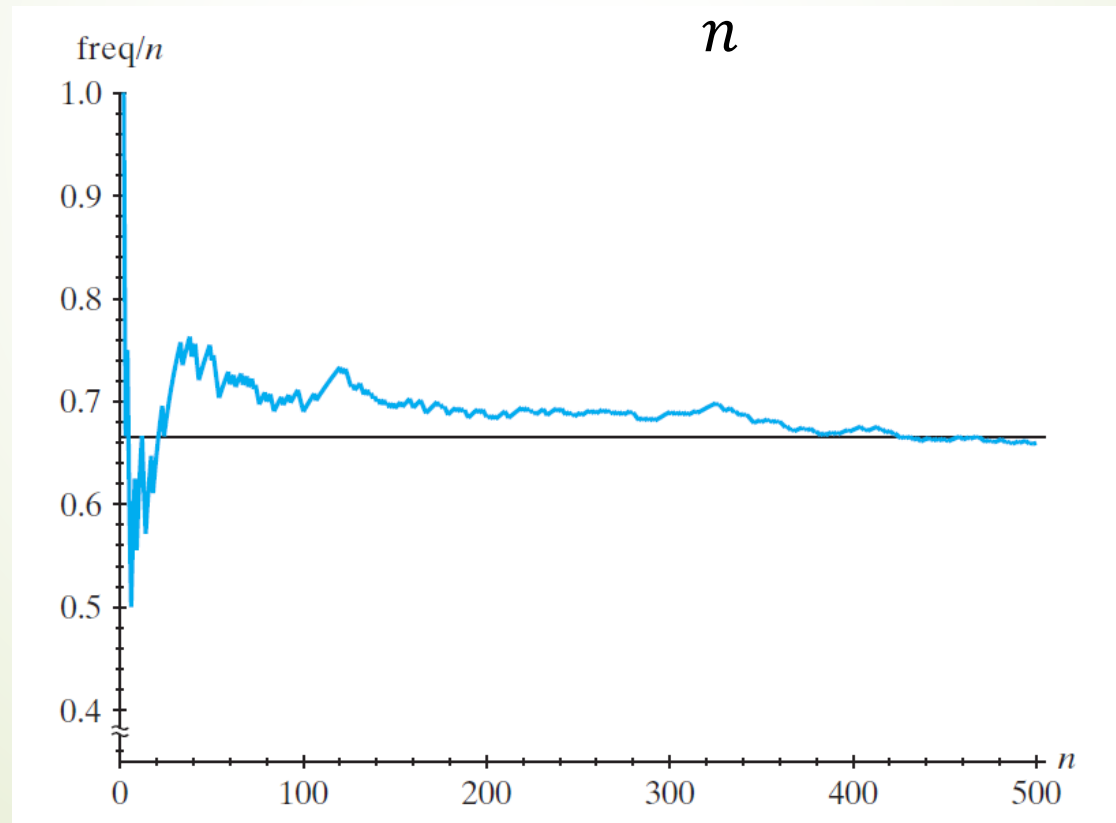
➤ Event A has happened

Event A is said to have happened **if the outcome of the experiment is in A**.

What is probability?

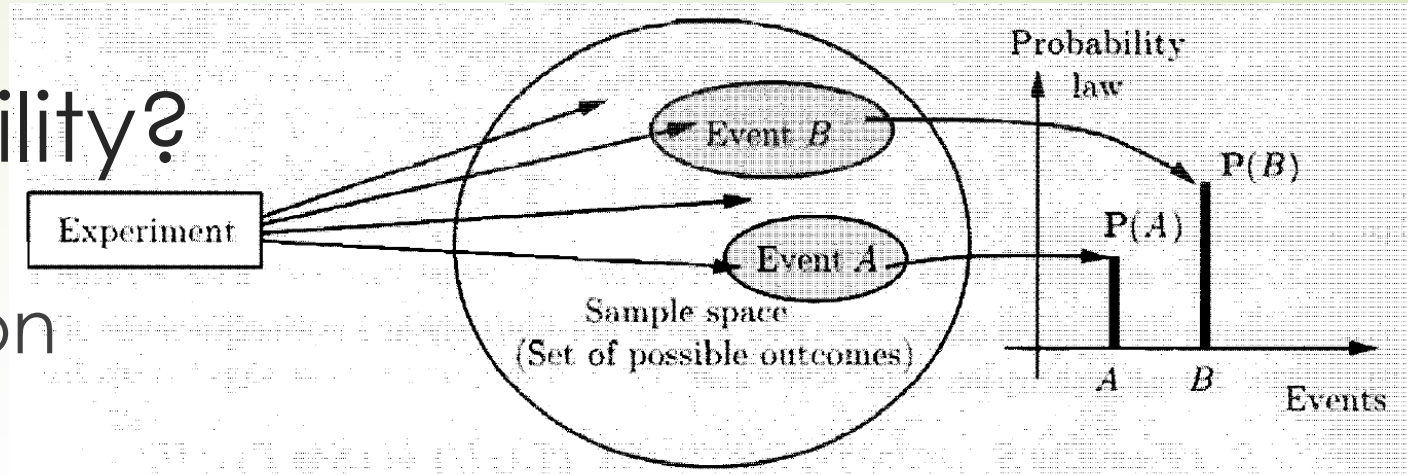
- Relative frequency

$$\lim_{n \rightarrow \infty} \frac{\text{number of times that event } A \text{ has happened in } n \text{ experiments}}{n}$$



What is probability?

► Probability function



Definition 1.1-1

Probability is a real-valued set function P that assigns, to each event A in the sample space S , a number $P(A)$, called the probability of the event A , such that the following properties are satisfied:

- (a) $P(A) \geq 0$;
- (b) $P(S) = 1$;
- (c) if A_1, A_2, A_3, \dots are events and $A_i \cap A_j = \emptyset, i \neq j$, then

$$P(A_1 \cup A_2 \cup \dots \cup A_k) = P(A_1) + P(A_2) + \dots + P(A_k)$$

for each positive integer k , and

$$P(A_1 \cup A_2 \cup A_3 \cup \dots) = P(A_1) + P(A_2) + P(A_3) + \dots$$

for an infinite, but countable, number of events.

What is probability?

► Properties of Probability function

$$P(A) = 1 - P(A').$$

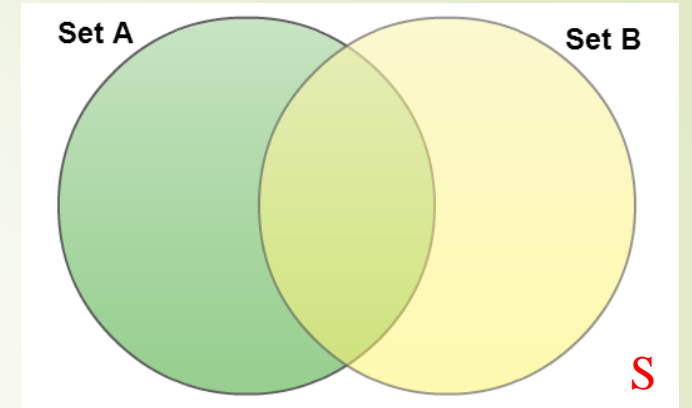
$$P(\emptyset) = 0.$$

If events A and B are such that $A \subset B$, then $P(A) \leq P(B)$.

For each event A , $P(A) \leq 1$.

If A and B are any two events, then

$$P(A \cup B) = P(A) + P(B) - P(A \cap B).$$



“Equally likely” and counting techniques



- If the outcomes are “equally likely”, i.e.,

$$P(\{e_i\}) = \frac{1}{m}, \quad i = 1, 2, \dots, m. \quad S = \{e_1, e_2, \dots, e_m\}$$

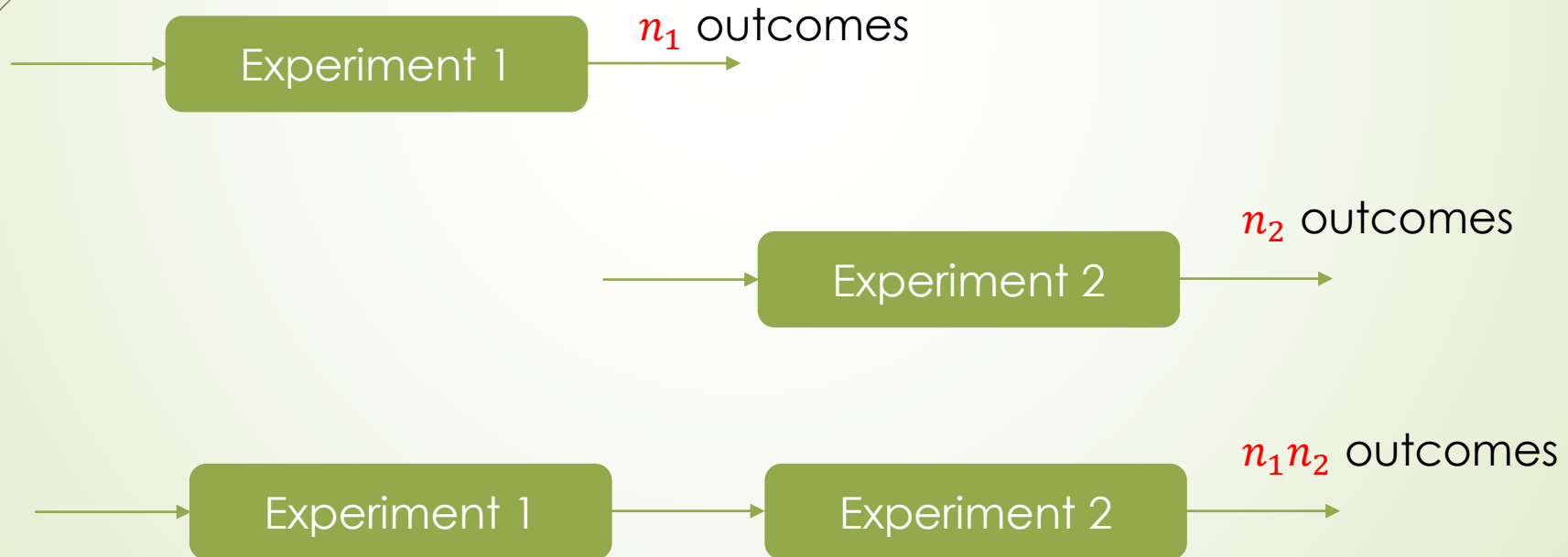
then

$$P(A) = \frac{\text{number of outcomes in } A}{\text{number of outcomes in } S}$$

The problem of computing $P(A)$ becomes the problem of counting the number of outcomes in the set A .

“Equally likely” and counting techniques

► Multiplication principle



Conditional Probability

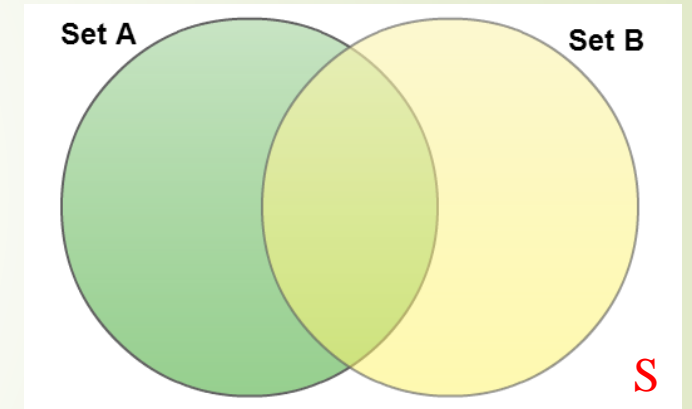
- The **conditional probability** of an event A , given that event B has occurred, is defined by

$$P(A | B) = \frac{P(A \cap B)}{P(B)}$$

provided that $P(B) > 0$.

1. Conditional probability is a probability.
2. The sample space shrinks from S to B .
3. $P(A \cap B) = P(A)P(B | A)$ $P(A \cap B) = P(B)P(A | B)$

25 balloons on a board, of which 10 balloons are yellow, 8 are red, and 7 are green. Probability of that the first two balloons hit are yellow?



Independent events

- ▶ Events A and B are **independent** if and only if $P(A \cap B) = P(A)P(B)$. Otherwise, A and B are called **dependent** events.
- ▶ If A and B are independent events, then the following pairs of events are also independent:
(a) A and B' ; (b) A' and B ; (c) A' and B' .
- ▶ Events A , B , and C are **mutually independent** if and only if

(a) A , B , and C are pairwise independent; that is,

$$P(A \cap B) = P(A)P(B), \quad P(A \cap C) = P(A)P(C),$$

and

$$P(B \cap C) = P(B)P(C).$$

(b) $P(A \cap B \cap C) = P(A)P(B)P(C)$.



Bayes Theorem

Assume that

1. S is a sample space and B_1, B_2, \dots, B_m are mutually exclusive and exhaustive w.r.t. the sample space S
2. The prior probabilities of $B_i, i=1, \dots, m$, are positive

Then

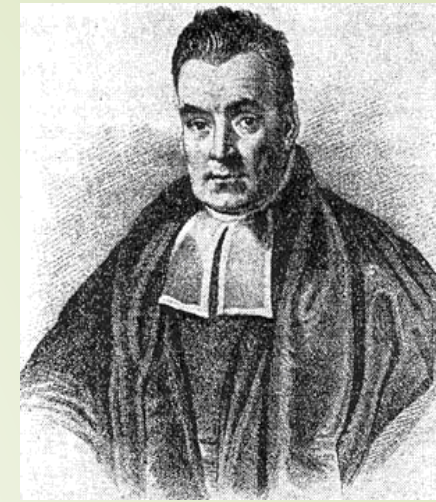
a) For any event A

$$\begin{aligned} P(A) &= \sum_{i=1}^m P(B_i \cap A) \\ &= \sum_{i=1}^m P(B_i)P(A | B_i) \end{aligned}$$

Prior probability
Posterior probability
Likelihood

b) If $P(A) > 0$

$$P(B_k | A) = \frac{P(B_k)P(A | B_k)}{\sum_{i=1}^m P(B_i)P(A | B_i)}$$



Univariate Random Variable

► pmf and pdf

Given a discrete or continuous RV $X: S \rightarrow X(S) \subset R$, or simply X defined on $D \subset R$, we define accordingly a pmf or pdf to assign the probability for the RV:

1. pmf for discrete RV: $f(x): D \rightarrow [0, 1]$
 $f(x) \geq 0, x \in D; \sum_{x \in D} f(x) = 1; P(x \in A) = \sum_{x \in A} f(x), A \subset D$
2. pdf for continuous RV: $f(x): D \rightarrow [0, \infty)$
 $f(x) \geq 0, x \in D; \int_D f(x) dx = 1; P(x \in [a, b]) = \int_a^b f(x) dx$
3. cdf for RV: $F(x) = P(X \leq x), x \in D$

for continuous RV, $F^{(1)}(x) = f(x), x \in D$

Univariate Random Variable

- Mathematical expectation [average value of $u(X)$]

$$E[u(X)] = \begin{cases} \sum_{x \in D} u(x)f(x), & \text{discrete RV} \\ \int_D u(x)f(x)dx, & \text{continuous RV} \end{cases}$$

- Properties of mathematical expectation

1. If c is a constant, $E[c] = c$
2. If c is a constant and $u(X)$ is a function of X , $E[cu(X)] = cE[u(X)]$
3. If c_1, c_2 are constants and $g_1(X), g_2(X)$ are functions of X ,
 $E[c_1g_1(X) + c_2g_2(X)] = c_1E[g_1(X)] + c_2E[g_2(X)]$

Characteristics of RV

- Mean [average value of X]

$$E[X]$$

- Variance [measure of the dispersion or spread out of X]

$$\text{Var}[X] = E(X - E[X])^2$$

$\sqrt{\text{Var}(X)}$ - standard deviation

- r th order Moments

$$E[X^r]$$

- mgf[uniquely characterizes the distribution of the RV]

$M(t) = E(e^{tX})$, $|t| < h$, if there is $h > 0$ such that $E(e^{tX})$ exists.

$$M(0) = 1, M^{(1)}(0) = E[X], M^{(2)}(0) = E[X^2], M^{(r)}(0) = E[X^r]$$



Bivariate Random Variable

- ▶ The outcome of the random experiment is a tuple of several things of interests.
- ▶ Joint pmf and joint pdf

Given a discrete or continuous RV X defined on D , we define accordingly a pmf or pdf to assign the probability for the RV:

1. pmf for discrete RV: $f(x, y): D \rightarrow [0, 1]$

$$f(x, y) \geq 0, (x, y) \in D; \sum_{(x,y) \in D} f(x, y) = 1,$$

$$P((x, y) \in A) = \sum_{(x,y) \in A} f(x, y), A \subset D$$

2. pdf for continuous RV: $f(x, y): D \rightarrow [0, \infty)$

$$f(x, y) \geq 0, (x, y) \in D; \iint_D f(x, y) dx dy = 1;$$

$$P((x, y) \in A) = \iint_A f(x, y) dx dy, A \subset D$$

Bivariate Random Variable

► Marginal pmf and marginal pdf

Given two discrete or continuous RVs X, Y defined on D and their joint pmf or joint pdf $f(x, y)$, we define accordingly the marginal pmf or marginal pdf to **assign the probability for the RV X** :

$D_X = \{\text{all possible values of } X \text{ in } D\}, D_Y = \{\text{all possible values of } Y \text{ in } D\}$

1. marginal pmf for discrete RV: $f_X(x): D_X \rightarrow [0, 1]$

$$f_X(x) = \sum_{y \in D_Y} f(x, y)$$

with the understanding $f(x, y) = 0, (x, y) \notin D$

2. marginal pdf for continuous RV: $f_X(x): D_X \rightarrow [0, \infty)$

$$f_X(x) = \int_{D_Y} f(x, y) dy$$

with the understanding $f(x, y) = 0, (x, y) \notin D$

Bivariate Random Variable

Mathematical Expectation

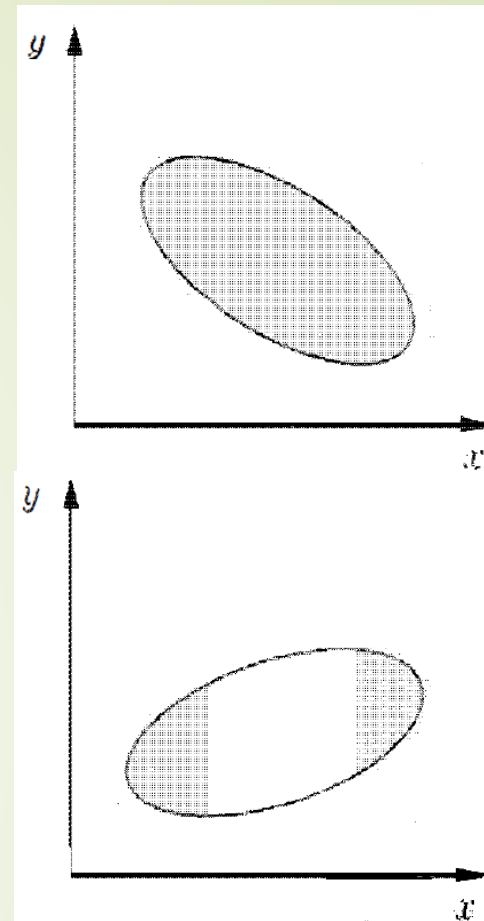
$$E[u(X, Y)] = \begin{cases} \sum_{(x,y) \in D} u(x, y) f(x, y), & \text{discrete RV} \\ \iint_D u(x, y) f(x, y) dx dy, & \text{continuous RV} \end{cases}$$

Covariance and Correlation Coefficient

$$\text{Cov}(X, Y) = E[(X - E[x])(Y - E[Y])]$$

$$\rho(X, Y) = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)}\sqrt{\text{Var}(Y)}}, \quad |\rho| \leq 1$$

1. $\text{Cov}(X, Y) > 0, \rho > 0, (X - E[x])$ and $(Y - E[Y])$ tend to have the same sign; $\rho = 1 \Rightarrow X - E[x] = c(Y - E[Y])$ with $c > 0$
2. $\text{Cov}(X, Y) < 0, \rho < 0, (X - E[x])$ and $(Y - E[Y])$ tend to have the opposite sign; $\rho = -1 \Rightarrow X - E[x] = c(Y - E[Y])$ with $c < 0$



Bivariate Random Variable

Independent Random Variables

X and Y are said to be independent if and only if

$$f(x, y) = f_X(x)f_Y(y)$$

A necessary condition for X and Y to be independent

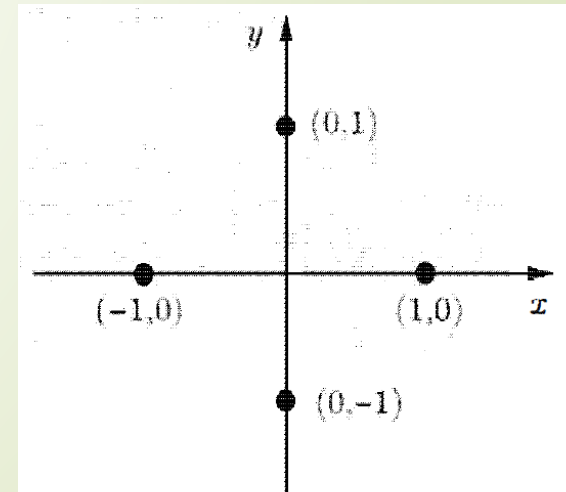
$$D = D_X \times D_Y$$

Independence



Uncorrelation

1. The **converse** is **not true** in general.
2. The **converse** is however **true** for **multivariate normal (Gaussian) distribution**.



Bivariate Random Variable

► Conditional pmf and Conditional pdf

Given two discrete or continuous RVs X, Y defined on D and their joint pmf or joint pdf $f(x, y)$, and marginal pmf or marginal pdf $f_X(x)$ to assign the probability for the RV Y given that $X = x$:

$$h(y|x) = \frac{f(x,y)}{f_X(x)}, f_X(x) > 0$$

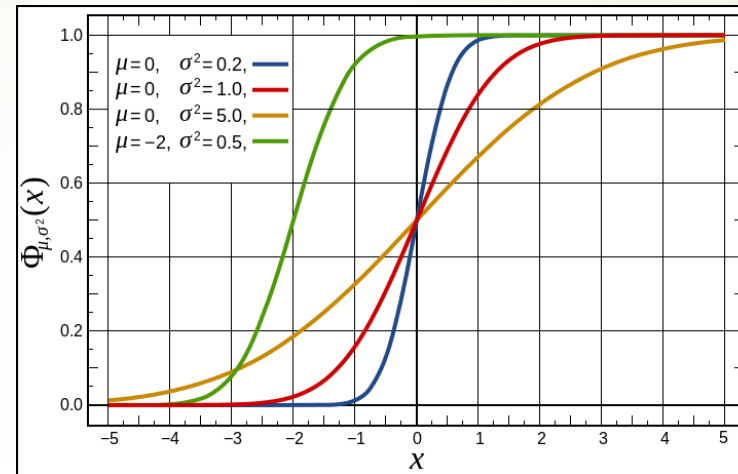
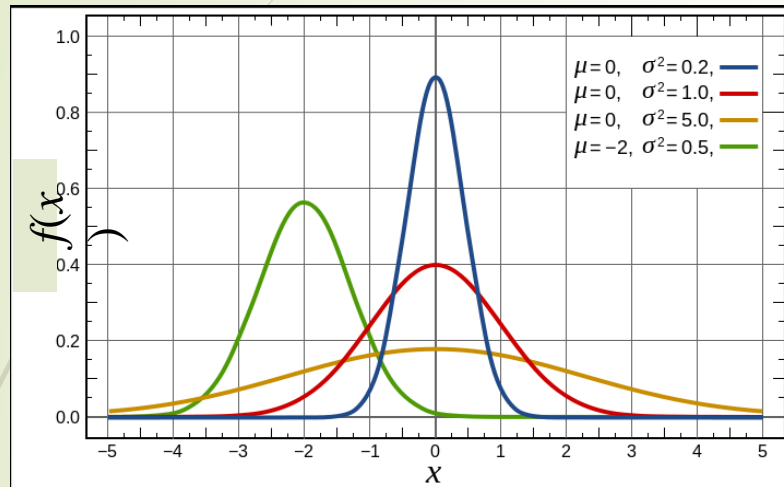
$$g(x|y) = \frac{f(x,y)}{f_Y(y)}, f_Y(y) > 0$$

► Conditional mathematical expectation

$$E[u(Y)|X = x] = \begin{cases} \sum_{y \in D_Y} u(y)h(y|x), & \text{discrete RV} \\ \int_{D_Y} u(y)h(y|x)dx, & \text{continuous RV} \end{cases}$$

Normal (Gaussian) distribution

Univariate Normal distribution



$$X \sim N(\mu, \sigma^2) \text{ if } f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(x-\mu)^2}{2\sigma^2}\right], \quad -\infty < x < \infty,$$

$$E[X] = \mu, \text{Var}[X] = \sigma^2, M(t) = \exp(\mu t + \frac{1}{2}\sigma^2 t^2)$$

$$\frac{X - \mu}{\sigma} \sim N(0,1) \Rightarrow$$

$$P(a \leq X \leq b) = P\left(\frac{a-\mu}{\sigma} \leq \frac{X-\mu}{\sigma} \leq \frac{b-\mu}{\sigma}\right) = \Phi\left(\frac{b-\mu}{\sigma}\right) - \Phi\left(\frac{a-\mu}{\sigma}\right)$$

$$P(Z \leq z) = \Phi(z) = \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} e^{-w^2/2} dw$$

$$\Phi(-z) = 1 - \Phi(z)$$

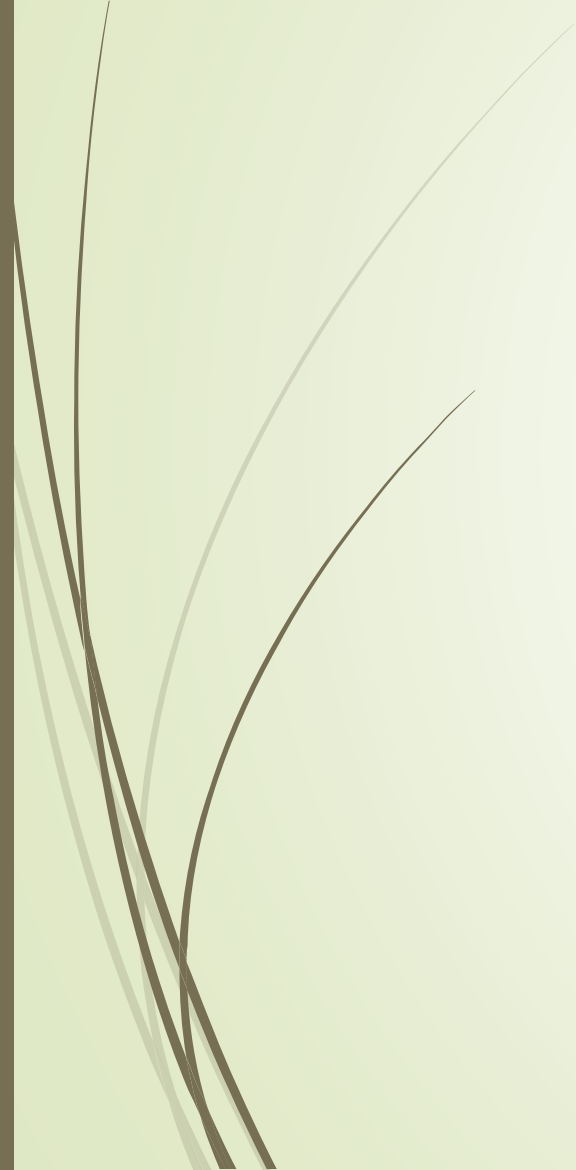
z	0.00	0.01	0.02	0.03	0.04	0.05	0.06
0.0	0.5000	0.5040	0.5080	0.5120	0.5160	0.5199	0.5239
0.1	0.5398	0.5438	0.5478	0.5517	0.5557	0.5596	0.5636
0.2	0.5793	0.5832	0.5871	0.5910	0.5948	0.5987	0.6026

Normal (Gaussian) distribution

► Bivariate Normal distribution

1. Marginal pdf and conditional pdf are all normal.
2. Independence is equivalent to uncorrelation!





The End